

# Accelerated Deep Learning Advances in HPC

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## Background/Approach

- Deep Learning Method: distributed data-parallel approach to train deep neural networks → Python framework using high-level Keras library with Google Tensorflow backend
  - major contrast with “Shallow Learning” approaches including SVM’s, Random Forests, Single Layer Neural Nets, etc. – including (i) deployment of accelerators (e.g., modern GPU’s); and (ii) move from DL software deployment on clusters to supercomputers:
    - *Titan (ORNL), Summit-Dev (ORNL); Piz Daint (CSCS); Tsubame-3 (TiTech) + Intel Systems – Cori (LBNL), Theta (ANL)*
  - stochastic gradient descent (SGD) used for large-scale (i.e., optimization on supercomputers) with parallelization via mini-batch training to reduce communication costs
- DL Supercomputer Challenge: scaling studies to examine if convergence rate saturates with increasing mini-batch size (to thousands of GPU’s)

## APPLICATION TOPIC: FUSION ENERGY SCIENCE

### SITUATION ANALYSIS

Most critical problem for Fusion Energy: avoid/mitigate large-scale major disruptions

•Approach: Use of big-data-driven statistical/machine-learning (ML) predictions for the occurrence of disruptions in EUROFUSION facility “Joint European Torus (JET)”

•Current Status: ~ 8 years of R&D results (led by JET) using Support Vector Machine (SVM) ML on zero-D time trace data executed on CPU clusters yielding ~ reported success rates in mid-80% range for JET 30 ms before disruptions , BUT > 95% with false alarm rate < 3% actually needed for ITER (Reference – P. DeVries, et al. (2015))

•Princeton Team Goals include:

(i)improve physics fidelity via development of new ML multi-D, time-dependent software including better classifiers;

(ii)develop “portable” (cross-machine) predictive software beyond JET to other devices and eventually ITER; and

(iii)enhance execution speed of disruption analysis for very large datasets

→ development & deployment of advanced ML software via Deep Learning Recurrent Neural Networks

# CLASSIFICATION

- Binary Classification Problem:
  - *Shots are Disruptive or Non-Disruptive*
- Supervised ML techniques:
  - *Physics domain scientists combine knowledge base of observationally validated information with advanced statistical/ML predictive methods.*
- Machine Learning (ML) Methods Engaged:

Basic SVM approach initiated by JET team producing “APODIS” software leading now to Princeton’s New Deep Learning Fusion Recurrent Neural Net (FRNN) code
- Approach: (i) examine appropriately normalized data; (ii) use training set to generate model; (iii) use trained model to classify new samples
  - Multi-D data analysis requires new signal representations;
  - FRNN software includes Deep Learning Convolutional and Recurrent Neural Net features.

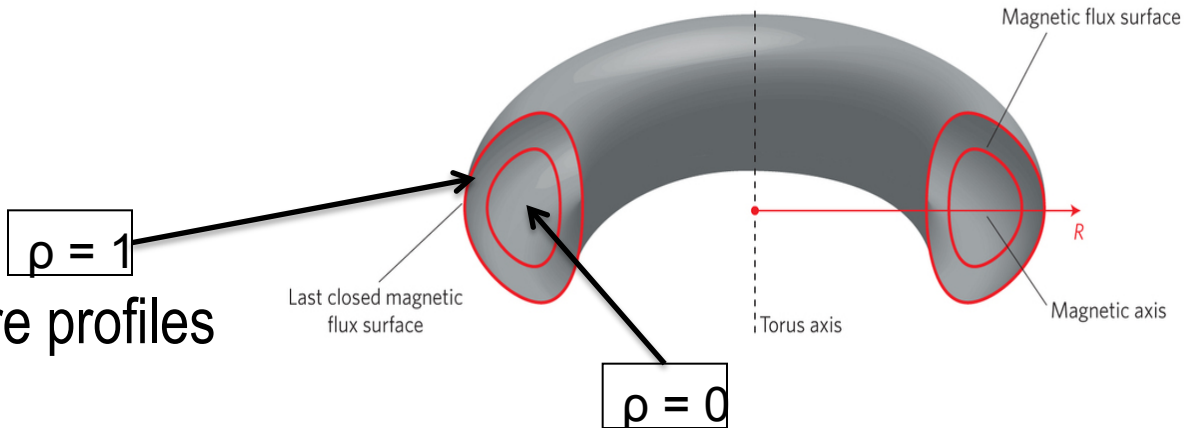
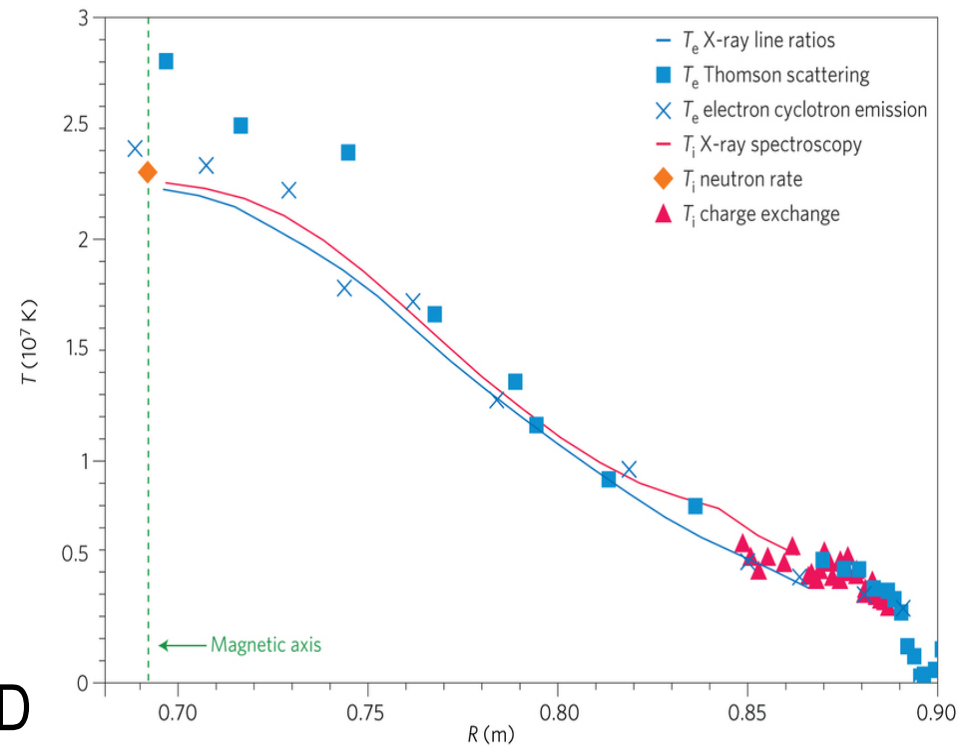
# Challenges & Opportunities

## Higher Dimensional Signals

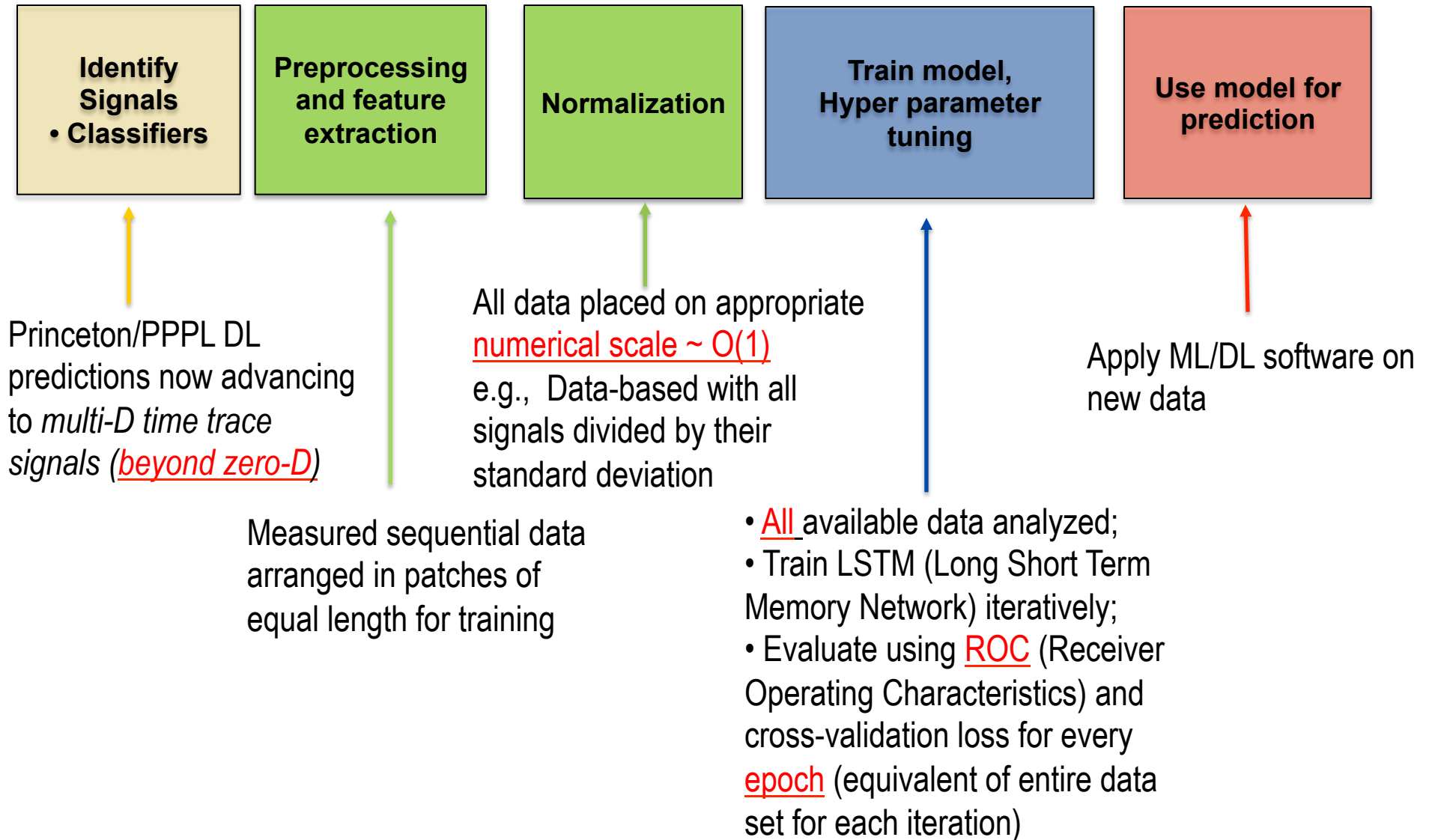
- At each timestep: **arrays** instead of **scalars**
- All as a function of  $\rho$  (normalized flux surface)
- Raw 1D profile  $\rightarrow$  convolution, optimize pooling for most salient features
- Full feature vectors/arrays include zero-D plus 1D

- Examples:

- 1D Current profiles
- 1D Electron temperature profiles
- 1D Radiation profiles



# Machine Learning Workflow



## JET Disruption Data

# Shots	Disruptive	Nondisruptive	Totals
Carbon Wall	324	4029	4353
Beryllium Wall (ILW)	185	1036	1221
Totals	509	5065	5574

JET produces ~  
Terabyte (TB) of  
data per day

JET studies → 9 Signals of zero-D (scalar) time traces, including	Data Size (GB)
Plasma Current	1.8
Mode Lock Amplitude	1.8
Plasma Density	7.8
Radiated Power	30.0
Total Input Power	3.0
d/dt Stored Diamagnetic Energy	2.9
Plasma Internal Inductance	3.0

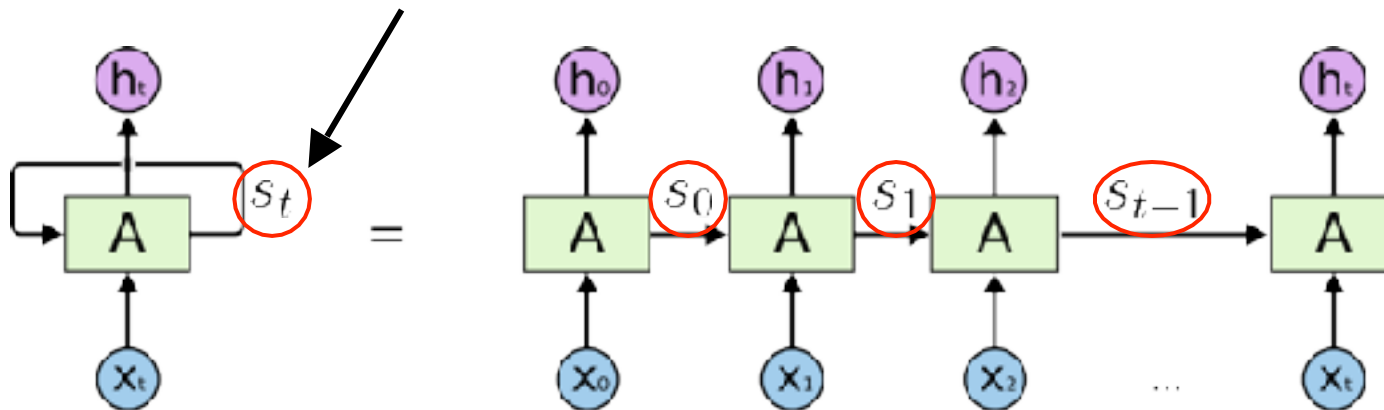
~55 GB data  
collected from  
each JET shot

→ Well over 350 TB total  
amount with multi-  
dimensional data yet to  
be analyzed

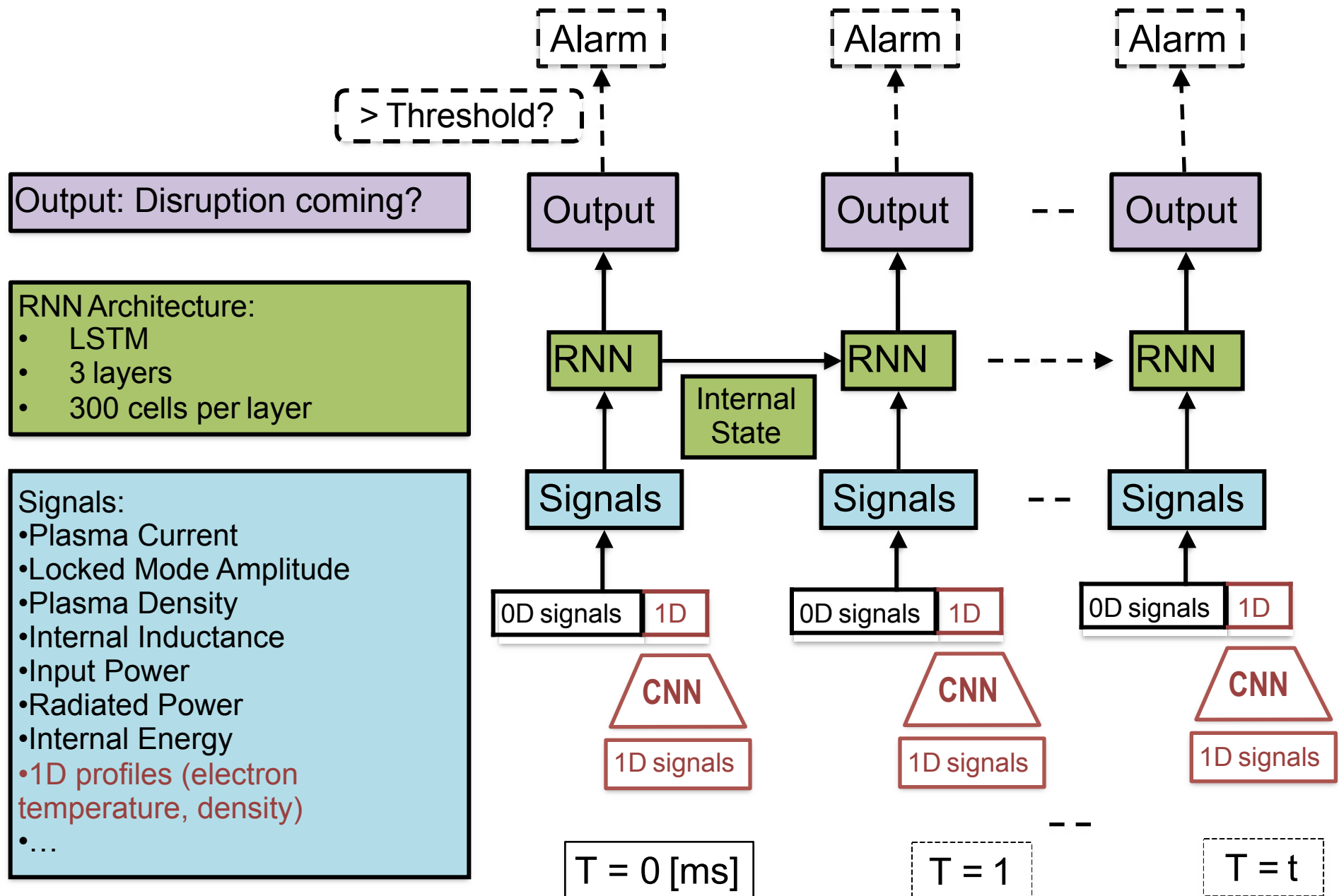
# Deep Recurrent Neural Networks (RNNs): Basic Description

- “Deep”
  - Learn salient representation of complex, higher dimensional data
- “Recurrent”
  - Output  $h(t)$  depends on input  $x(t)$  & internal state  $s(t-1)$

*Internal State (“memory/context”)*



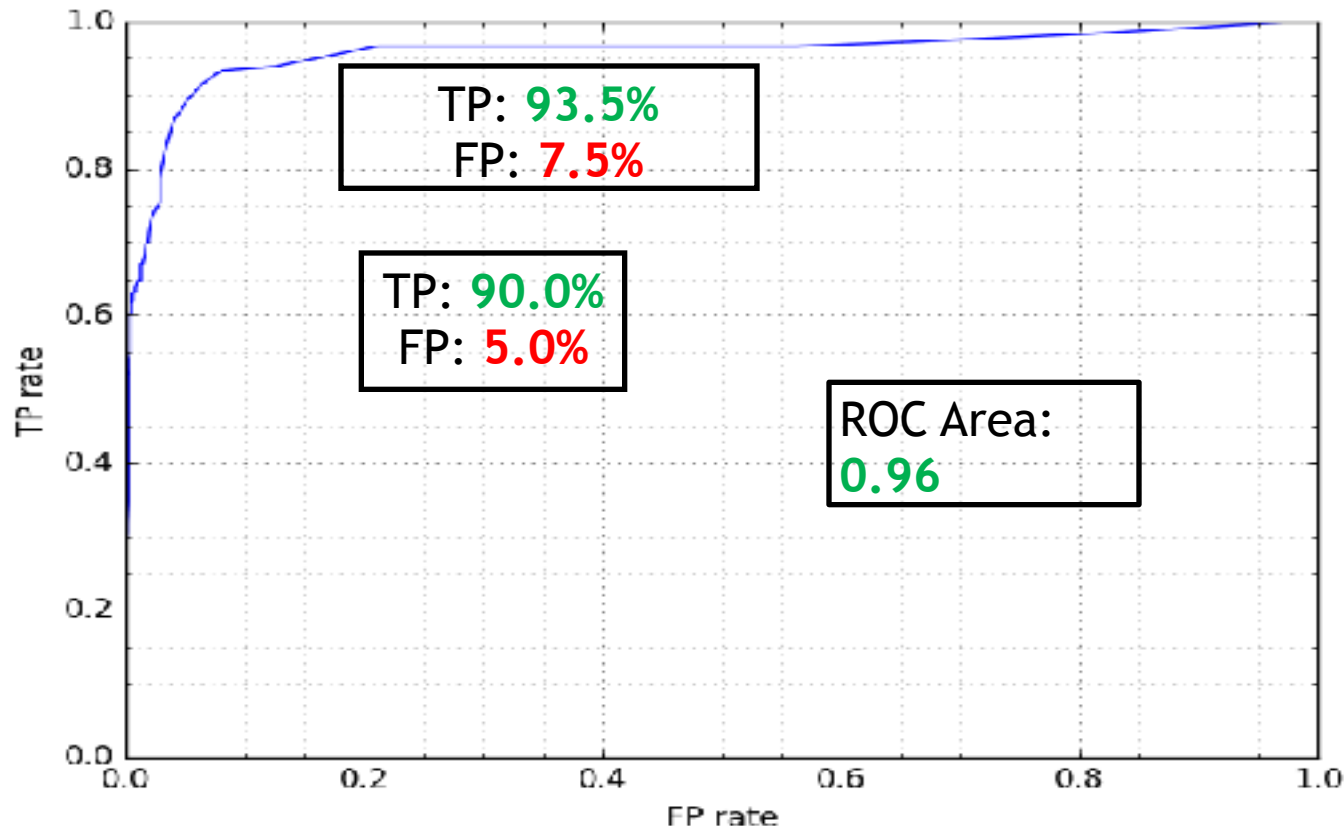
# Deep Recurrent Neural Nets: Schematic



# FRNN Code PERFORMANCE: ROC CURVES

## JET ITER-like Wall Cases @30ms before Disruption

Performance Tradeoff: Tune **True Positives** (good: correctly caught disruption) vs. **False Positives** (bad: safe shot incorrectly labeled disruptive).



**Data (~50 GB), 0D signals:**

- Training: on **4100 shots** from **JET C-Wall** campaigns
- Testing **1200 shots** from **Jet ILW** campaigns
- **All shots used**, no signal filtering or removal of shots

# RNNs: HPC Innovations Engaged

## GPU training

- Neural networks use dense tensor manipulations, efficient use of GPU FLOPS
- Over 10x speedup better than multicore node training (CPU's)

## Distributed Training via MPI

### Linear scaling:

- Key benchmark of “time to accuracy”: we can train a **model that achieves the same results nearly N times faster with N GPUs**

### Scalable

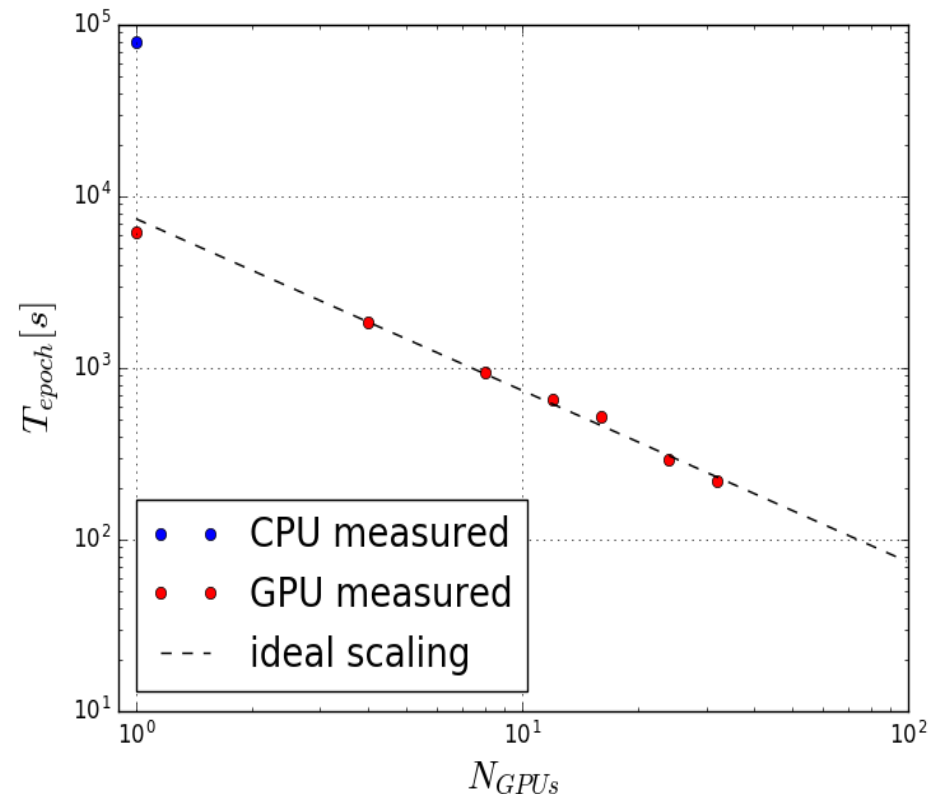
- to 100s or >1000's of GPU's on Leadership

### Class Facilities

- TB's of data and more

- Example: Best model training time on full dataset (~40GB, 4500 shots) of 0D signals training

- **SVM (JET) : > 24hrs**
- **RNN ( 20 GPU's ) : ~40min**



# Fusion Recurrent Neural Net (FRNN) Description

- **Python deep learning code** for disruption prediction in fusion (tokamak) experiments
  - Reference: <https://github.com/PPPLDeepLearning/plasma-python>
- Implements distributed data parallel synchronous RNN training
  - Tensorflow & Theano backends with MPI for communication
  - FRNN code workflow is characteristic of typical distributed deep learning software
  - Core modules:
    - **Models:** Python classes necessary to construct, train, and optimize deep RNN models.
    - **Pre-process:** arrange data into patches for stateful training; normalize
    - **Primitives:** Python objects for key plasma physics abstractions
    - **Utils:** a set of auxiliary functions for pre-processing, performance evaluation, and learning curves analysis

## Scaling Summary

**Communication:** each batch of data requires time for synchronization

$$T_{sync} \sim \log(N_{workers})$$

**Runtime:** computation time

$$T \sim \frac{1}{N} (A + B \log(N)) = O\left(\frac{\log(N)}{N}\right)$$

**Parallel Efficiency**

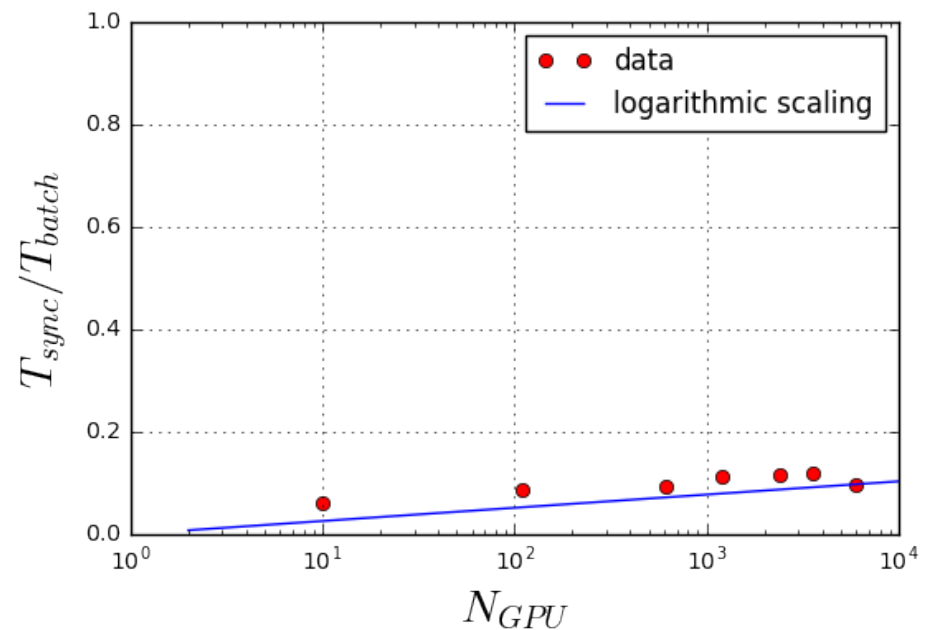
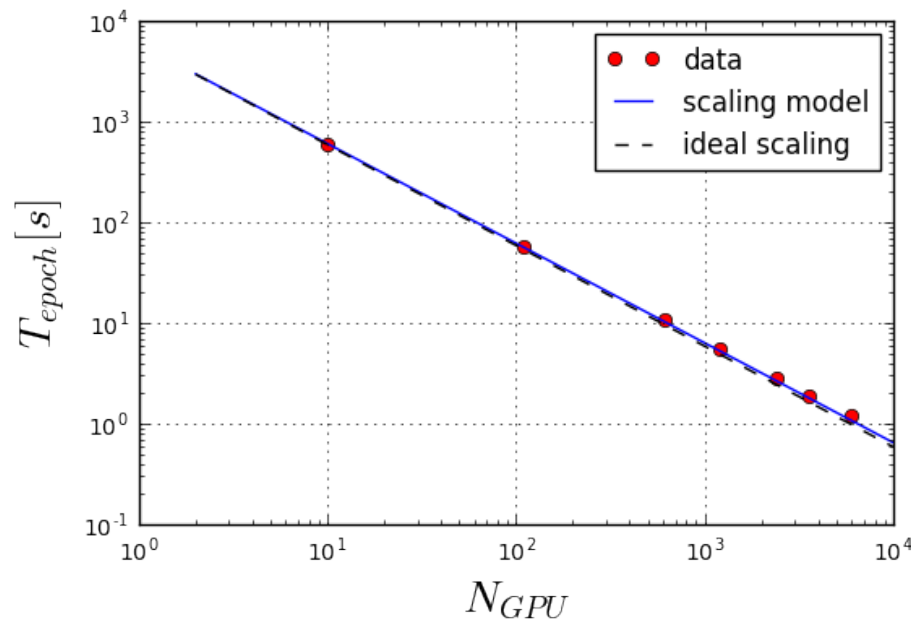
$$\text{Parallel Efficiency} \sim \frac{A + B}{A + B \log(N)} = o\left(\frac{1}{\log(N)}\right)$$

# FRNN Scaling Results on GPU's

- Tests on OLCF Titan CRAY supercomputer
  - OLCF DD AWARD: Enabled Scaling Studies on Titan currently up to 6000 GPU's
  - Total ~ 18.7K Tesla K20X Kepler GPUs



## Tensorflow+MPI



## CURRENT PERSPECTIVE

Forecasting disruptions using machine learning is an important application of a **general idea**:

- Use multi outcome prediction to **distinguish disruption types/scenarios**
- Beginning now to move from ***prediction to active control*** (including new experimental proposals on the U.S. DIII-D tokamak in San Diego, CA)
- Increasingly large and diverse data sets require building ***scalable systems to take advantage of leadership class computing facilities***

## Fusion Deep Learning (FRNN) Technical Summary

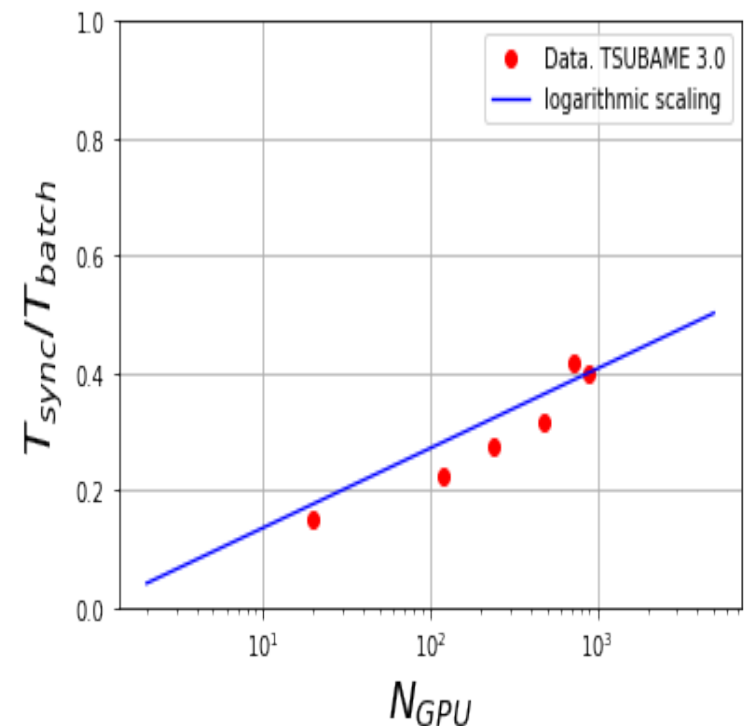
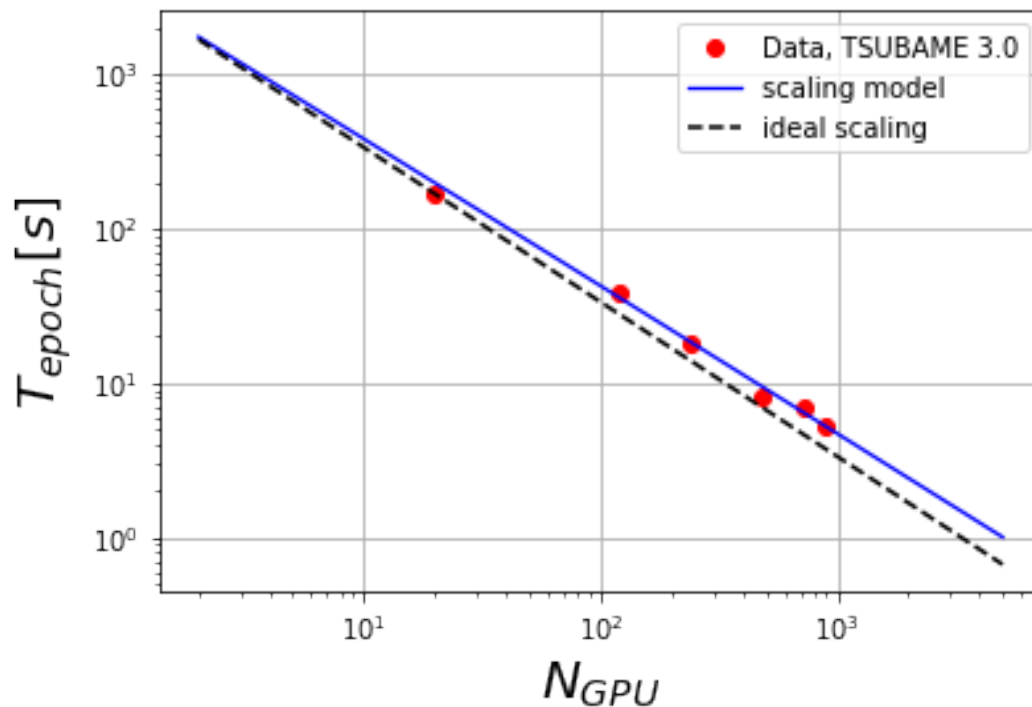
- FRNN → a distributed data-parallel approach to train deep neural networks (stacked LSTM's);
- Replica of the model is kept on each “worker” → processing different mini-batches of the training dataset in parallel;
- Results on each worker are combined after each epoch using MPI;
- Model parameters are synchronized via parameter averaging → with learning rate adjusted after each epoch to improve convergence
- **Stochastic gradient descent (SGD)** used for large-scale optimization with parallelization via mini-batch training to reduce communication cost.
- **Challenge:** scaling studies to examine if convergence rate saturates/ decreases with increasing mini-batch size (to thousands of GPU's).
- **Targeted Large HPC Systems with P-100's for Performance Scaling**
- Studies:** (1) “TSUBAME 3” @ TITECH with ~ 3K GPU's – “Grand Challenge Runs”; (2) “PIZ-DAINT” Cray XC50 @ CSCS (Switzerland) with > 4K GPU'S; (3) “SUMMIT-DEV” @ OLCF leading to SUMMIT with VOLTA GPU's

# New FRNN scaling tests: TSUBAME 3.0

Very recent results: TSUBAME 3.0 supercomputer (TiTech, Tokyo, Japan)

Tsubame 3.0 initial “Grand Challenge Runs”

- *Order of thousand Tesla P100 SXM2 GPUs, 4 GPUs per node, NVlink*
- *Tensorflow+MPI, CUDA8, CuDNN 6, OpenMPI 2.1.1, GPU Direct*



## Fusion Deep Learning (FRNN) Technical Summary (continued)

NVIDIA Volta GPU's → to be key element of 200 PF SUMMIT @ OLCF

Associated Challenge: requires **training neural networks with “half-precision floats”**

- Single-Precision → 32 bits (8 bits for exponent, 23 for fraction and 1 for sign)
- Double-Precision → 64 bits

NOTE: FRNN code has produced many results with single precision - float32 and has now developed new **half-precision float** - 5 bits exponent, 10 bit fraction and 1 bit sign

REFERENCE: *half-precision float deployment of FRNN with cross-benchmarking of new results vs. earlier single precision results → paper to be presented at SC'17 (Denver, CO)– includes description of changes in the weight update during SGD (Stochastic Gradient Descent) method to prevent vanishing gradients due to lower precision.*

- Looking forward to testing new half-precision FRNN software capability on NVIDIA Volta GPU's at OLCF

## Fusion Deep Learning (FRNN) Technical Summary (continued)

→ [GOOGLE Article on Tensor Processing Units in Cloud:](#)

"Build and Train Machine Learning Models on our new Google Cloud TPU's"  
(Tensor Processing Units)

<https://blog.google/topics/google-cloud/google-cloud-offer-tpus-machine-learning/>

The highlighted description highlights [potential delivery of 11.5 PF of compute power to expedite training!](#)

### **Possible FRNN Software Relevance:**

Since FRNN software already uses the TensorFlow backend, our current plan is to try the [Google Cloud TPU's](#) -- beginning with their offer of [free access to 1000 Cloud TPU's via the TensorFlow Research Cloud](#) – for which we have applied.

→ **APPROACH:** *Comparison of time to prediction and associated deep learning neural nets training rates on supercomputers vs. that on the new Google Cloud TPU's promises to be quite informative.*

# Fusion Big Data ML/DL Application Summary

- **Fusion Energy Mission:**

- Accelerate demonstration of the *scientific & technical feasibility of delivering Fusion Power*
- Most critical associated problem is to *avoid/mitigate large-scale major disruptions.*

- **ML Relevance to HPC:**

- **Rapid Advances** on development of predictive methods via large-data-driven *“machine-learning” statistical methods*
- **Approach Focus:** *Deep Learning/Recurrent Neural Nets (RNNs)*
- **Significance:** *Exciting alternative predictive approach to “hypothesis-driven/first principles” exascale predictive methods*

**\*\*\* Convergence/Complementarity:** *Physics-centric path-to-exascale **HPC needed to introduce/establish improved Supervised ML Classifiers with associated features***

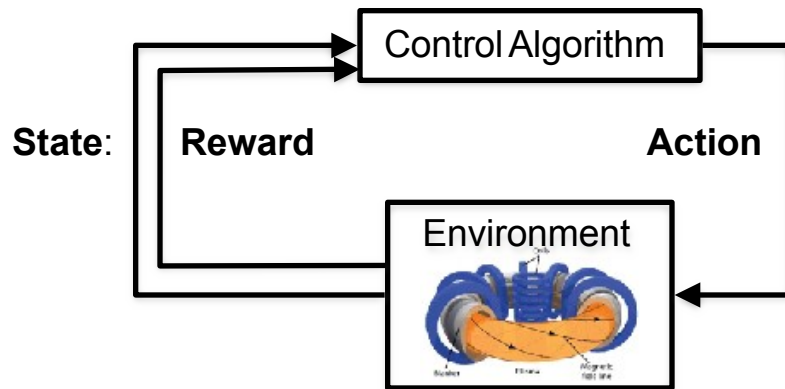
- **Associated Challenge:**

→ *Improvements over zero-D SVM-based machine-learning needed to achieve > 95% success rate, <5% false positives at least 30 ms before disruptions -- with portability of software to ITER via enhanced physics fidelity (capturing multi-D) with improvement in execution time enabled by access to advanced HPC hardware (e.g., large GPU and possibly other supercomputing systems).*

# Takeaways: Deep Learning Analysis

Use **Higher-dimensional signals**

Automatically learn **cross-machine, generalizable features**



Take advantage of **world class HPC**

Go from **prediction to control**  
(**deep reinforcement learning**)

